



# ***MREM 76***

*APS mini Plus reader modules*

*User's guide*



# ***techfass®***

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## 2 Product description

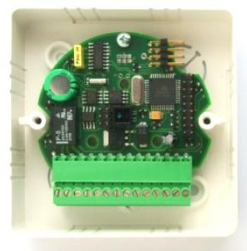
The **MREM 76**<sup>1)</sup> reader modules (125 kHz readers with an embedded single door controller) are designed for connection to the RS 485 bus of the **APS mini Plus** access control system, or for standalone operation. It is possible to connect up to 32 reader modules to a single line of the APS mini Plus system. In effect the number of lines is not limited.

The reader module is available in various modifications differing in the way of use.

### 2.1 MREM 76 module

Reader module for general use designed for applications with remote antenna module (*Pic. 1*).

The module can be installed wherever using a standard module is inappropriate for mechanical or security reasons. Reading range is dependent on the type of the antenna module and its frequency tune-up; this is why it is not recommended to adjust the cable supplied with the original antenna module.



*Pic. 1: MREM 76 without cover*

### 2.2 MREM 76E module

Complete reader module designed for installation into round installation boxes with inner diameter 68 mm. All-purpose conception of the module's board enables installation in most of the electrical devices' cover designs in blocks of flats and therefore adjust the appearance of the reader modules to the appearance of other devices designed by an architect (*Pic.2*).



*Pic. 2: MREM 76E + KU68 box*

### 2.3 MREM 76.BTW and MREM 76.BTS module

Applied reader module in an installation box KU68 with a cover panel in Bticino Light design in white (MREM 76.BTW, *Pic. 3a*) or silver (MREM 76.BTS, *Pic.3b*) color.



*Pic. 3 a: MREM 76.BTW*



*Pic. 3 b: MREM 76.BTS*

<sup>1)</sup> Commercial designation of available versions is described in *table 1*.

### 3 Technical parameters

#### 3.1 Product version

| Product version | Product designation | Product housing               | Catalogue number | Module features <sup>2)</sup> |    |
|-----------------|---------------------|-------------------------------|------------------|-------------------------------|----|
|                 |                     |                               |                  | TF                            | EM |
|                 | MREM 76 – TF        | <i>LK 80, no antenna</i>      | 53476200         | ✓                             | ✗  |
|                 | MREM 76E – TF       | <i>Designed for KU 68</i>     | 53476000         | ✓                             | ✗  |
|                 | MREM 76.BTS – TF    | <i>Bticino Light - Silver</i> | 53476400         | ✓                             | ✗  |
|                 | MREM 76.BTW – TF    | <i>Bticino Light - White</i>  | 53476600         | ✓                             | ✗  |
|                 | MREM 76 – EM        | <i>LK 80, no antenna</i>      | 53476201         | ✓                             | ✓  |
|                 | MREM 76E – EM       | <i>Designed for KU 68</i>     | 53476001         | ✓                             | ✓  |
|                 | MREM 76.BTS – EM    | <i>Bticino Light - Silver</i> | 53476401         | ✓                             | ✓  |
|                 | MREM 76.BTW – EM    | <i>Bticino Light - White</i>  | 53476601         | ✓                             | ✓  |

Table 1: Product version

<sup>2)</sup> **TF** – TECHFASS factory 125 kHz ID media reading; **EM** – 125 kHz ID media reading;

#### 3.2 Technical features

|                    |                                      |                       |   |
|--------------------|--------------------------------------|-----------------------|---|
| Technical features | Supply voltage                       |                       | 8 ÷ 15 VDC  |
|                    | Current demand                       | Typical               | 95 mA   |
|                    |                                      | Maximal               | 130 mA  |
|                    | Version with keypad                  |                       | N/A   |
|                    | ID technology, typical reading range | EM Marin              | 6 cm (with ISO card)  |
|                    | Real-time clock                      |                       | Yes, with 24 hrs. back-up   |
|                    | Memory                               | Cards                 | 2,000 ID, 2 programming cards   |
|                    |                                      | Events                | 3,400   |
|                    |                                      | Time schedules        | 64  |
|                    | Inputs                               | 1 <sup>st</sup> input | Logical potential-free contact  |
|                    |                                      | 2 <sup>nd</sup> input | Logical potential-free contact  |
|                    | Outputs                              | Door lock             | Relay NC/NO, 2A/24V   |
|                    |                                      | Alarm                 | Transistor output 5V/5mA  |
|                    | I/O Port                             | External device       | Ext. tamper / ext. reader buzzer control / module disable function / reading synchronization MASTER/SLAVE modes |
|                    | Indicators                           |                       | 3x LED<br>1x PIEZO  |
|                    | Tamper protection                    |                       | Opto-electronic   |
|                    | Communication interface              |                       | RS 485  |
|                    | Alternative data input / output      |                       | WIEGAND (configurable)  |

Table 2: Technical features

### 3.3 Antenna and special accessories




|                     |          |          |   |
|---------------------|----------|----------|---|
| Special accessories | AEM 12.1 | 51400301 | Antenna module for hidden assembly (buzzer present, no LED)                       |
|                     |          |          |  |
|                     | AEM 13.1 | 51400401 | Antenna module with a ferrite coil for Targha panels (buzzer present, no LED)     |
|                     |          |          |  |
|                     | WIO 22   | 51901200 | Remote control module, 2x relay   |
|                     |          |          |  |

Table 3: Special accessories

### 3.4 Using WIO 22 module for remote output control

The **WIO 22** remote control **WIEGAND** relay module is designated for secure output control of APS system reader modules. The door open or other functions can be controlled from the module located inside the secure area, while the reader module can be located in the non-secure area.

The module is controller by **WIEGAND** signal directly from the reader module working in standard operating mode. The module must be paired with appropriate reader module before use.

### 3.5 MREM 76 mechanical design

|        |                       |                          |
|--------|-----------------------|--------------------------|
| Design | Weight                | 0.033 kg                 |
|        | Operating temperature | -10°C ÷ +40°C            |
|        | Humidity              | Max. 75%, non-condensing |
|        | Environment           | Indoor                   |
|        | Dimensions            | 81x81x25 mm              |

Table 4 a): MREM 76 mechanical design

### 3.6 MREM 76E mechanical design

|        |                       |   |
|--------|-----------------------|---|
| Design | Weight                | 0.018 kg                                |
|        | Operating temperature | -10°C ÷ +40°C                           |
|        | Humidity              | Max. 75%, non-condensing                |
|        | Environment           | Indoor                                  |
|        | Dimensions            | Suitable for Ø 68 mm installation boxes |

Table 4 b): MREM 76E mechanical design

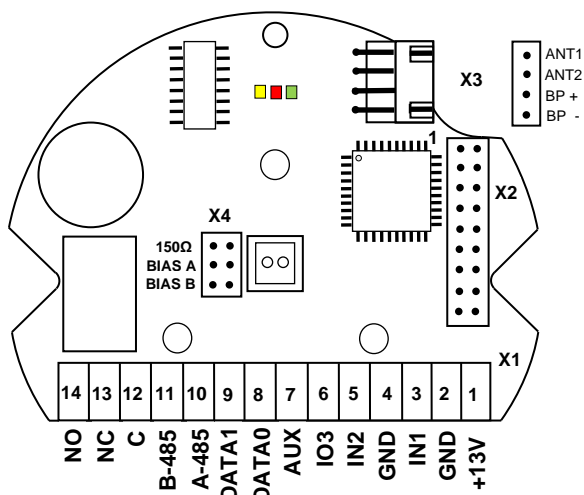
### 3.7 MREM 76.BTW and MREM 76.BTS mechanical design

|        |                       |   |
|--------|-----------------------|---|
| Design | Weight                | 0.102 / 0.160 kg (W/S)                      |
|        | Operating temperature | -10°C ÷ +40°C                               |
|        | Humidity              | Max. 75%, non-condensing                    |
|        | Environment           | Indoor                                      |
|        | Color                 | White (MREM 76.BTW)<br>Silver (MREM 76.BTS) |
|        | Dimensions            | 90x80x55 mm                                 |

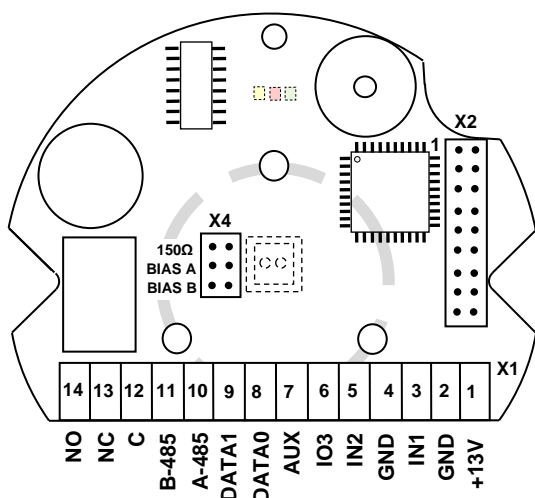
Table 4 c): MREM 76.BTW and MREM 76.BTS mechanical design

## 4 Installation

### 4.1 Terminals and jumpers



Pic. 4 a): MREM 76



Pic. 4 b): MREM 76E, MREM 76.BTW,  
MREM 76.BTS

|        |          |                      |
|--------|----------|----------------------|
| Ad. X2 | X2.1 ÷ 5 | HW address (A0 ÷ A4) |
|        | X2.6     | Reserved             |
|        | X2.7 ÷ 9 | Factory use          |

Table 5: Address jumpers X2

|                         |    |                        |
|-------------------------|----|------------------------|
| Terminal description X1 | 1  | Supply voltage +13,8 V |
|                         | 2  | Supply voltage 0 V     |
|                         | 3  | Input 1                |
|                         | 4  | 0 V                    |
|                         | 5  | Input 2                |
|                         | 6  | I/O Port 3             |
|                         | 7  | Alarm output           |
|                         | 8  | Wiegand DATA 0         |
|                         | 9  | Wiegand DATA 1         |
|                         | 10 | A cable - RS 485 line  |
|                         | 11 | B cable - RS 485 line  |
|                         | 12 | Relay C                |
|                         | 13 | Relay NC               |
|                         | 14 | Relay NO               |

Table 6: Terminal description X1

|           |        |                           |
|-----------|--------|---------------------------|
| RS 485 X4 | 150 Ω  | Line termination          |
|           | BIAS A | Idle state definition (A) |
|           | BIAS B | Idle state definition (B) |

Table 7: Line settings X4

|              |      |            |
|--------------|------|------------|
| Connector X3 | ANT1 | Antenna    |
|              | ANT2 | Antenna    |
|              | BP + | Buzzer (+) |
|              | BP - | Buzzer (-) |
|              | LEDY | Yellow LED |
|              | LEDG | Green LED  |
|              | LEDR | Red LED    |
| GND          | GND  | Ground     |

Table 8: Antenna module connector X3

## 4.2 Standard connection

|            |                  |  |
|------------|------------------|--|
| Connection | Input 1          | Door contact, active when door closed; REX button  |
|            | Input 2          | Request to exit button or handle contact, active when button or handle pressed; Tamper; Disabling function   |
|            | Output 1 (relay) | Door lock control  |
|            | Alarm output     | Low power transistor output (+5 V in any alarm state)  |
|            | I/O Port 3       | External tamper (Standard operating mode)<br>External reader buzzer control (op. mode with entry reader)<br>Disabling function<br>Reading synchronization: MASTER / SLAVE mode |

Table 9: Standard connection

The door monitoring contact (IN1) is operational after its first change of status since switching on the module. Full door lock timing acc. to *tab. 11* is used when the door status contact is not installed and no Forced Door and Door Ajar alarms are triggered.

## 4.3 LED Indicators

|                |        |                           |                                  |
|----------------|--------|---------------------------|----------------------------------|
| LED indicators | Red    | Continuously lit          | Online operating mode via RS 485 |
|                |        | Flashing with 4 s period  | Offline operating mode           |
|                |        | Fast switching with green | Address setting mode             |
|                | Yellow | Continuously lit          | Programming mode                 |
|                |        | Flashing                  | Indicating door lock release     |
|                | Green  |                           | ID media reading                 |

Table 10: LED indicators

## 4.4 Installation instructions

The reader module uses passive RF/ID technology, which is sensitive to RF noise sources. Noise sources are generally of two types: radiating or conducting.

Conducted noise enters the reader via wires from the power supply or the host. Sometimes, switching power supplies generate enough noise to cause reader malfunction, it is recommended to use linear system power supplies.

Radiated noise is transmitted through the air. It can be caused by computer monitors or other electrical equipment generating electromagnetic fields.

Consequently, a short distance between the reader modules themselves can cause reading malfunctions – for correct operation it is necessary to keep a minimum distance of 50 cm. Various metallic constructions may have a negative influence on this distance; if there are any doubts, it is recommended to perform a practical test before final mounting.

Nearby metal surfaces may cause a decrease in reading distance and speed. This is caused by the combined effects of parasitic capacitance and conductance.



## 5 Setting parameters of the reader module

### 5.1 Configurable parameters

| Configurable parameters | Parameter  | Possible range  | Default setting    |
|-------------------------|--|---|--------------------|
|                         | Door lock release time                                   | 0 ÷ 255 s   | 7 s                |
|                         | Door lock control setting                                | Direct / reverse  | Direct             |
|                         | Door lock relay function setting                         | Standard / toggle / pulse   | Standard           |
|                         | Permanent door lock release according to a time schedule | Never / Schedule index  | Never              |
|                         | Door lock status indication                              | YES / NO  | NO                 |
|                         | Acoustic signal of door lock release                     | YES / NO  | YES                |
|                         | Door ajar time   | 0 ÷ 255 s   | 20 s               |
|                         | First input configuration                                | Door contact / REX button   | Door contact       |
|                         | Second input configuration                               | REX button / handle contact / external tamper / tamper / disabling function | REX button         |
|                         | Third input / output port                                | Tamper / ext. buzzer signal / disabling function / reading synchronization  | Tamper             |
|                         | Acoustic signalization time - Tamper                     | 0 ÷ 255 s   | 30 s               |
|                         | Acoustic signalization time - Forced door                | 0 ÷ 255 s   | 30 s               |
|                         | Acoustic signalization time – Door ajar                  | 0 ÷ 255 s   | 0 s                |
|                         | Acoustic signalization time – APB alarm                  | 0 ÷ 255 s   | 0 s                |
|                         | Signalization time – Card alarm                          | 0 ÷ 255 s   | 30 s               |
|                         | Antipassback function setting                            | See <i>chapter 6.10</i>   | Disabled           |
|                         | Automatic summer time adjustment                         | YES / NO  | YES                |
|                         | Release lock with REX button when tamper alarm active    | YES / NO  | YES                |
|                         | Online authorization timeout                             | 0 ÷ 25500 ms  | 800 ms             |
|                         | Standalone authorization after timeout                   | YES / NO  | YES                |
|                         | Saving events in the module's archive                    | Door opened   | Enabled / Disabled |
|                         |  | Door closed   | Enabled / Disabled |
|                         |  | Input 2 On  | Enabled / Disabled |
|                         |  | Input 2 Off   | Enabled / Disabled |
|                         |  | Strike released   | Enabled / Disabled |
|                         |  | Strike closed   | Enabled / Disabled |

Table 11: Configurable parameters

### 5.2 Reader module parameters setting

Detailed instructions for setting reader module parameters are described in the *APS Reader configuration program user's guide* available at the address [http://www.techfass.cz/files/m\\_aps\\_minipus\\_reader\\_en.pdf](http://www.techfass.cz/files/m_aps_minipus_reader_en.pdf).

## 5.3 HW address setting

HW address setting is defined by the configuration of address jumpers X2.1 ÷ 5, see *Tab.5* and *Tab.12*.

Keep in mind that every module on the line must be set to a different unique address. When any address is duplicated the address conflict appears on system bus and the system cannot work properly.

| Address jumpers X2 | Address | 1  | 2  | 3  | 4  | 5  | 6  | 7  | 8  | 9  | 10 | 11 | 12 | 13 | 14 | 15 | 16 |
|--------------------|---------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
|                    | X2.1    | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  |
|                    | X2.2    | ○  | ●  | ●  | ○  | ○  | ●  | ●  | ○  | ○  | ●  | ●  | ○  | ○  | ●  | ●  | ○  |
|                    | X2.3    | ○  | ○  | ○  | ●  | ●  | ●  | ●  | ○  | ○  | ○  | ○  | ●  | ●  | ●  | ●  | ○  |
|                    | X2.4    | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ○  |
|                    | X2.5    | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ●  |
|                    | Address | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 | 32 |
|                    | X2.1    | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  | ●  | ○  |
|                    | X2.2    | ○  | ●  | ●  | ○  | ○  | ●  | ●  | ○  | ○  | ●  | ●  | ○  | ○  | ●  | ●  | ○  |
|                    | X2.3    | ○  | ○  | ○  | ●  | ●  | ●  | ●  | ○  | ○  | ○  | ○  | ●  | ●  | ●  | ●  | ○  |
|                    | X2.4    | ○  | ○  | ○  | ○  | ○  | ○  | ○  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ○  |
|                    | X2.5    | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ●  | ○  |

Table 12: Address jumpers X2

Legend: ● ... set (ON) ○ ... removed (OFF)

Reader module's reset is required after any change of address setting, disconnect and connect the supply voltage again.

## 6 Reader module functioning

The reader module supports the following functions:

- Standard "Door Open" function.
- Door status monitoring.
- Exit-devices contact monitoring.
- Alarm output activated / acoustic signalization activated when any alarm condition occurs.

The "Door Open" function can be activated in 3 different ways:

- Reading a valid ID (card, key fob...).
- Pressing the exit button (according to configuration) – cannot be used in alarm condition.
- Via communication line (program request).

### 6.1 "Door Open" function description

In case the *standard function of the door lock relay* is set, the door lock is *released* and the *beeper activated* (when not disabled) when the "Door Open" function is activated. Both

outputs stay active until the door is opened or the preset door lock release time has elapsed - see *configuration table*.

In case the *toggle function of the door lock relay* is set, the door lock relay status is *switched* and the *beeper* is *activated* (when not disabled) when the "Door Open" function is activated. The beeper stays active until the door is opened or the preset door lock release time has elapsed - see *configuration table*. The door lock relay status remains unchanged until another "Door Open" function is activated.

In case the *pulse function of the door lock relay* is set, the door lock relay status is switched for the time defined by the *Pulse width* parameter (ms) after the Door Open function is activated.

In case the standard function of the door lock relay is set, reading a valid card during door lock release resets the door lock release time.

## **6.2 Function permanent door lock release according to a time schedule**

When the function is set, the door lock is permanently released when relevant time schedule is valid. Reading a valid ID is standardly announced via the communication line (in online operating mode). The forced door alarm cannot be raised when the door lock is permanently released.

The permanent door lock release function and the toggle function of the door lock relay are mutually exclusive.

## **6.3 Alarm states**

The reader module can get in following alarm states:

- 1) Tamper alarm
- 2) Forced door alarm
- 3) Door ajar alarm
- 4) Antipassback alarm (Time APB alarm, Zone APB alarm)
- 5) ID with Alarm flag alarm

Alarm state reporting is performed as follows:

- Via communication line (statuses 1, 2, 3, 4, 5)
- By acoustic signal (beeper) (statuses 1, 2, 3, 4).
- Activating the alarm output (AUX output) (statuses 1, 2, 3, 5).

Alarm signaling via communication line requires online running PC with relevant software suitable for online operation (APS 400 nAdministrator).

Two ways of acoustic signaling is carried out:

- Steady signal (tamper).
- Intermittent signal (forced door and/or door ajar, APB alarm).

Acoustic alarm signaling is stopped after a valid ID is presented or pre-set time interval is elapsed, see the configuration table.

If any of the relevant alarm states (*with setting of the signaling timer > 0*) occurs, the alarm output is activated. It can control any alarm device directly or it can be processed further.

After terminating all alarm conditions the alarm output is deactivated.

The alarm signaling is triggered by any alarm condition.

### 6.3.1 Tamper alarm

In case of tampering the module (by opening the cover (optoelectronic sensor) or changing the status of input 2 or input 3 in proper configuration) the “Tamper” state is activated <sup>3)</sup>.

<sup>3)</sup> The Tamper alarm handling is operational after their first change of status since switching on the module. There is no need to configure the module when the tamper protection is not used.

### 6.3.2 Forced Door alarm

The “Forced Door” alarm state is activated when the door is opened without activating the “Door Open” function. The only exception is opening the door with the second module input IN2 active and configured as a handle contact.

### 6.3.3 Door Ajar alarm

If the door stays open until the pre-defined Door ajar timeout expires – see *Tab. 12*, the “Door Ajar” alarm is activated.

### 6.3.4 Antipassback alarm

The *Antipassback alarm* is raised when an ID is read during the *Time APB* counter is running or when the ID is blocked by a *Zone APB*.

### 6.3.5 ID with Alarm flag alarm

*ID with Alarm flag alarm* occurs when an ID with the Alarm flag is read.

### 6.3.6 Reading ID during alarm state

Reading an ID doesn't affect the alarm state, reading a valid ID only terminates the acoustic alarm announcement followed by “Door Open” function. Reading an invalid ID only interrupts the acoustic announcement of the alarm state while signaling “Invalid ID”.

## 6.4 Standard operating modes

The reader module can be in either *online* or *offline* operating mode. The module's functionality is identical in both operating modes; the events archive is read from the reader module's memory when the module goes online. When a programming card is read (while in either online or offline mode), the module goes into programming mode.

## 6.5 Read ID media format

### 6.5.1 EM Marin ID media format

The EM Marin ID media format can be changed into selected 24, 32 or 40 bits length of ID code. The default length is 40 bits. This setting is only used when unifying of the ID media codes length is required – in combined systems with WIEGAND output readers with a fixed WIEGAND data format IDs (more information in *APS Reader* user's guide available at [http://www.techfass.cz/files/m\\_aps\\_miniplus\\_reader\\_en.pdf](http://www.techfass.cz/files/m_aps_miniplus_reader_en.pdf)).

## 6.6 Wiegand interface configuration

### 6.6.1 Standard operating mode

This is the module default operating mode. The Wiegand interface is used for controlling the WIO 22 module in this configuration. When the reader module operates in the standard operating mode, the I/O Port (*tab. 6*) is used as an input for monitoring an external device tamper status.

### 6.6.2 Wiegand output

The module can be configured into a standard reader with a *WIEGAND output* in 26, 32, 42 or 44 bits format for *EM Marin* technology ID media. Read IDs are formatted with the previous setting first (see *chapter 6.5.1*), after that they are sent in the output format. When the reader module operates in the Wiegand output operating mode, the I/O Port (*tab. 6*) is used as an input for monitoring an external device tamper status.

| Wiegand | ID media technology | Available configuration of the WIEGAND output format |
|---------|---------------------|--|
|         | EM Marin            | 26bit, 32bit, 42bit, 44bit                           |

Table 13: ID media format in WIEGAND operating mode

Two long beeps and the red LED lit feature powering up the module. The green LED blink indicates an ID reading.

Individual signals function in *WIEGAND output* operating mode is described in *table 14*.

|         |                  |  |
|---------|------------------|--|
| Wiegand | Input 1          | Beeper control (0 V active)  |
|         | Input 2          | Yellow LED control (0 V active)  |
|         | Output 1 (relay) | Tamper signaling; it follows the alarm state of tamper sensors (tamper signal = relay switched on) <sup>3)</sup> |

*Table 14: Signal function in WIEGAND operating mode*

Since the *FW version 5.09* the reading synchronization of a *couple of TECHFASS readers* is implemented, enabling to *cancel the mutual disturbance* of the modules. The reader module offers the *Wiegand data interface synchronization* in *MASTER* mode.

### **6.6.3 Wiegand input (entry reader)**

The module can be configured into a mode of controlling the door from both sides (*entry reader mode*).

In the *entry reader mode* an identification at an external reader connected via the *WIEGAND interface* acquires a *reason code 255*; at the same time the reader module operates standardly, the reason codes equal zero.

When the reader module operates in the entry reader operating mode, the I/O Port (*tab. 6*) is used as an output for controlling the entry reader buzzer.

Since the *FW version 5.09* the reading synchronization of a *couple of TECHFASS readers* is implemented, enabling to *cancel the mutual disturbance* of the modules. The reader module offers the *Wiegand data interface synchronization* in *SLAVE* mode.

The *WIEGAND input* and *WIEGAND output* operating modes are mutually exclusive.

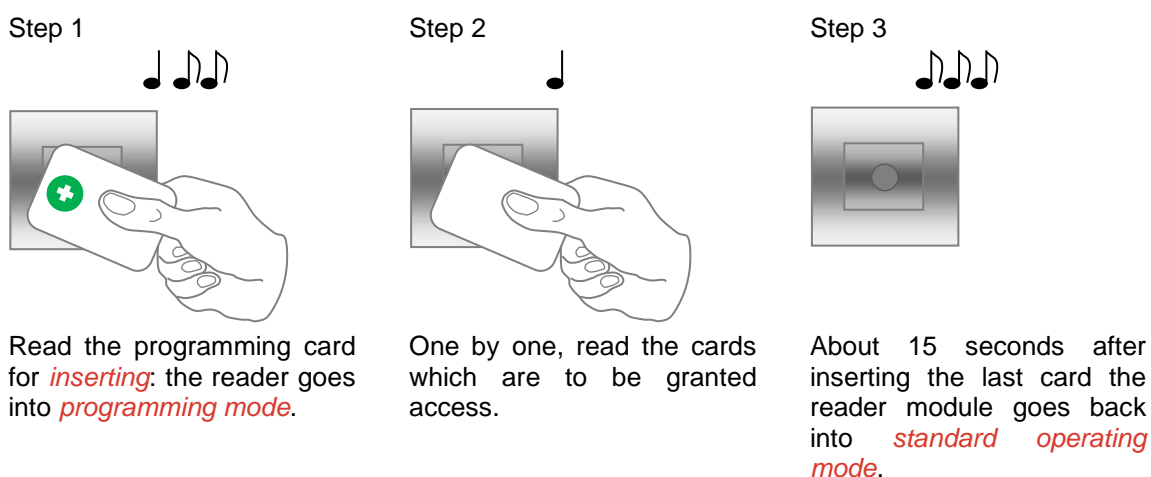
## 6.7 Programming mode

The module enters programming mode by reading one of the two *programming cards* (cards “+” and “-”). The programming mode cannot be entered while the module is in hardware address setting mode (for modules with HW address setting via the communication line). The module’s functionality in programming mode can be seen in *pictures 5 a-d*.

It is not possible to use time schedules when inserting cards in programming mode, therefore cards are always valid.

### 6.7.1 Inserting cards into the reader’s memory

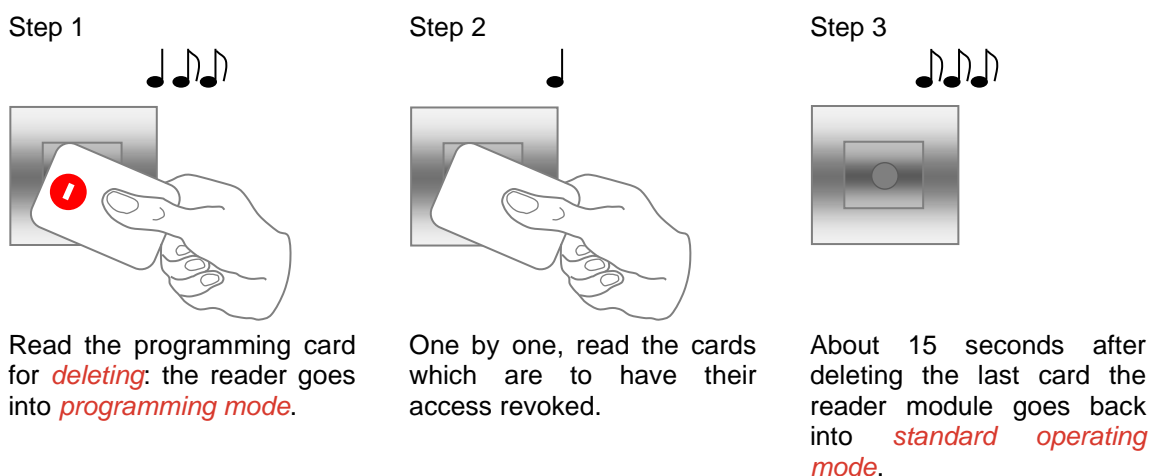
Follow these steps for inserting cards into the reader module’s memory:



*Pic.5 a): Inserting cards*

### 6.7.2 Deleting cards from the reader’s memory

For deleting the cards from the reader module’s memory use following steps:

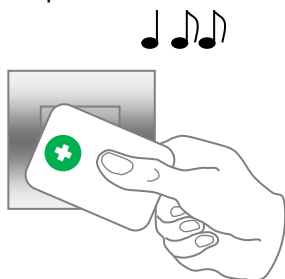


*Pic.5 b): Deleting cards*

## 6.7.3 Deleting cards „above or below“

If a user loses his ID medium, it is usually impossible to delete the ID from the memory with the procedure described in the previous chapter, since the medium is no longer available (with an exception of entering the code at the keypad). Following procedure can be used for deleting such ID. The procedure *requires using an ID medium*, which was inserted *right before or right after the ID medium*, which should be deleted.

Step 1



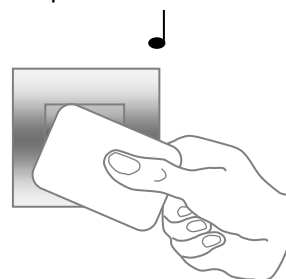
Read the programming card for *inserting*: the reader goes into *programming mode*, which is indicated by slow flashing of yellow LED.

Step 2



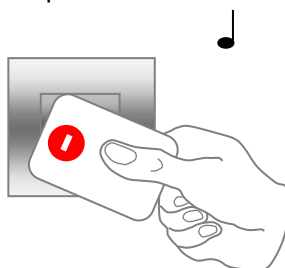
Read the programming card for inserting 5 times in a row; the reader will go into *Deleting cards „above or below“* mode indicated by fast flashing of yellow LED.

Step 3



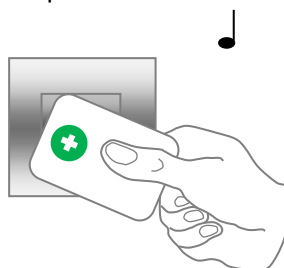
Read a card, which is located in the module's memory *right before or right after* the card you wish to delete. After this step the module quickly flashes with yellow LED.

Step 4 - A



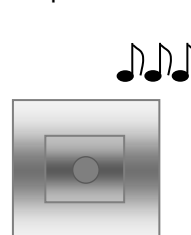
For deleting an ID located *right before* the ID used in previous step, read the programming card for *deleting*.

Step 4 - B



For deleting an ID located *right after* the ID used in previous step, read the programming card for *inserting*.

Step 5



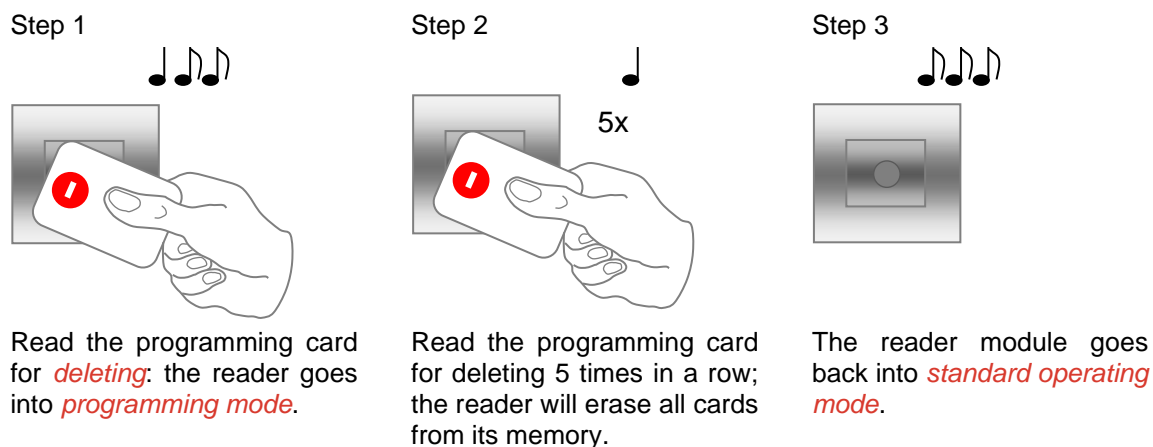
The reader module goes back into *standard operating mode*.

Pic.5 c): Deleting cards „above or below“



## 6.7.4 Deleting all cards from the reader's memory

Follow these steps for deleting all cards from the reader module's memory:



Pic.5 d): Deleting all cards

## 6.7.5 Recommended method for access rights management (using prog. cards)

In case of managing access rights of plenty of users (using programming cards only), it is appropriate to establish a table, which summarizes operation with the reader module memory. All operations (adding and deleting cards) should be stored in the table. Following example shows correct usage of the programming cards and proper filing of the actions:

- Inserting *5 new cards* using the procedure from chapter 6.7.1 – Read + *(inserting) programming card*, read *cards 1-5*, after 15 s the programming mode is exited, *create a table*.

| position | card   |
|----------|--------|
| 1        | card 1 |
| 2        | card 2 |
| 3        | card 3 |
| 4        | card 4 |
| 5        | card 5 |

Pic.5 e): Table after inserting 5 cards

- Card 3 gets lost* – Delete it *using the card 4*, which is available, and using the procedure from chapter 6.7.3 – Read + *(inserting) programming card*, then *5x* + *(inserting) programming card* again, then *card 4*, and finally – *(deleting) programming card*. *Register the change in your table*.

| position | card               |
|----------|--------------------|
| 1        | card 1             |
| 2        | card 2             |
| 3        | card 3 (lost)      |
| 4        | card 4 (available) |
| 5        | card 5             |

→

| position | card   |
|----------|--------|
| 1        | card 1 |
| 2        | card 2 |
| 3        | card 3 |
| 4        | card 4 |
| 5        | card 5 |

Pic.5 f): Deleting card 3 using the card 4, table after deleting card 3

- *Card 4 gets lost* – Delete it *using the card 2*, which is available, and using the procedure from *chapter 6.7.3 – Read + (inserting) programming card*, then *5x + (inserting) programming card* again, then *card 2*, and finally *+ (inserting) programming card* again. *Register the change in your table.*

| position | card               |   | position | card   |
|----------|--------------------|---|----------|--------|
| 1        | card 1             | → | 1        | card 1 |
| 2        | card 2 (available) |   | 2        | card 2 |
| 3        | card 3             |   | 3        | card 3 |
| 4        | card 4 (lost)      |   | 4        | card 4 |
| 5        | card 5             |   | 5        | card 5 |

Pic.5 g): Deleting card 4 using the card 2, table after deleting card 4

- It is necessary to *add another card* (card 6). We proceed with the procedure from *chapter 6.7.1* again. 1 – Read *+ (inserting) programming card*, read *cards 1-5*, after 15 s the programming mode is exited. *Register the change in your table.*

| position | card   |
|----------|--------|
| 1        | card 1 |
| 2        | card 2 |
| 3        | card 3 |
| 4        | card 4 |
| 5        | card 5 |
| 6        | card 6 |

Pic. 5 h): Table after inserting card 6

A new card is always inserted at the position after the last inserted card. In case of deleting all cards using the procedure described in *chapter 6.7.4*, it is necessary to create a new filing table.

## 6.8 ID expiration function

This function is implemented since the FW version 5.0.

It is possible to set an *Expiration date* for every *ID* stored in the module. When the date occurs, the ID becomes invalid (expired). The expiration evaluation is performed on every date change in the module's RTC and when the access rights are downloaded.

## 6.9 ID with Alarm flag function

This function is implemented since the FW version 5.0.

It is possible so set an *Alarm – ID flag* for every *ID* stored in the module. When the ID is read, relevant alarm is raised (and the alarm output is switched for preset time).

## 6.10 Antipassback function

This function is implemented since the FW version 5.0.

The Antipassback function is defined in two ways:

- **Time APB** – user cannot repeatedly use his ID for defined time
- **Zone APB** – user cannot repeatedly enter an area, where he is already present

The Antipassback function is used *only for the users*, whose access is driven by a *time schedule*. The users with access always granted are not affected by the Antipassback function.

The Antipassback flags for an *ID* can be *reset* by *inserting the ID again* with use of the *programming cards* (offline solution). *All Antipassback flags* are also *reset* whenever new *access rights data are downloaded* from the program.

Both Zone and Time Antipassback flags are written either immediately *after an ID is read*, or after relevant *door is opened* (relevant input is disconnected).

### 6.10.1 Time Antipassback

The *Time Antipassback* is defined by the *ABP timer initial value* (in minutes), which is set to the ID after passing at the reader module. If the users uses the ID at the address during the timer for the ID is running, the Time APB alarm is raised. Following parameters affect the Time APB function:

- *APB timer initial value* – defines the Time APB flag (timer) value set to the ID after passing at the reader module. If a user uses the ID again before the timer elapses, Time APB alarm is raised.
- *Open door after APB time alarm* – if the option is enabled, the Door open function is performed after the Time APB alarm is raised.

In case of using the operating mode Standard with Entry reader the time APB function is evaluated at the entry reader only.

### 6.10.2 Zone Antipassback

The *Zone Antipassback* is defined by *enabling the option* for the relevant address. The Zone APB flag is set for the ID when passing at the reader module. If a user uses the ID again when the Zone APB flag is set, the Zone APB alarm is raised. Following parameters affect the Zone APB function:

- *Enabled* – enable/disable general Zone APB flag setting.
- *Enable in offline mode* – if the option is not set, the module operates in offline mode like if the APB function was not implemented.
- *Open door after APB Zone alarm* – if the option is enabled, the Door open function is performed after the Zone APB alarm is raised.

### 6.11 *Disabling function*

This function is implemented since the *FW version 5.08*.

The *module disabling function* can be set at the second input and at the third input / output port. The logic of the function is individually configurable. The function is active whenever one or both of the configured inputs are active.

The module behavior is as described below when the disabling function is active:

- User with access driven by a time schedule cannot run the door open function
- User with access always granted is not affected by the disabling function
- Remote door open function cannot be performed
- Remote identification with ID is disabled for users with access driven by a time schedule

The disabling status changes and disabled actions are logged in the events archive.

### 6.12 *Reading synchronization*

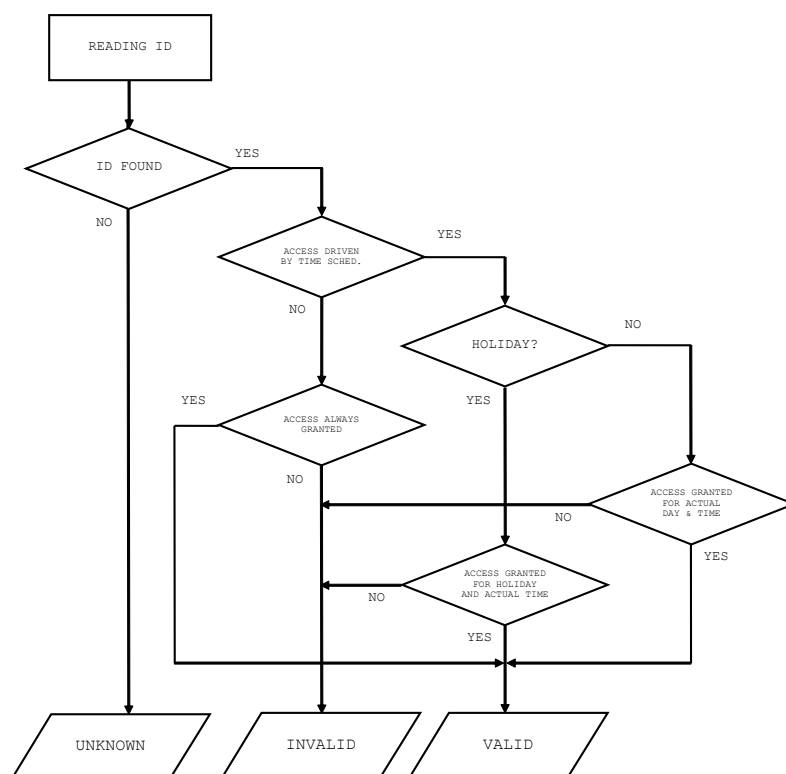
Since the *FW version 5.09* the reading synchronization of a *couple of TECHFASS readers* is implemented, enabling to *cancel the mutual disturbance* of the modules. The reader module offers to use the *IO synchronization* in both *MASTER* and *SLAVE* mode. The *input/output port 3* is used as the *synchronization signal*.

### 6.13 *Online authorization*

Since the *FW version 5.11* the *Online authorization of ID* can be used in APS mini Plus system. When the feature is used, the ID validity is resolved in connected PC. To be able to use this authorization mode, the reader module has to be equipped with a *MLO* license.

## 7 Simplified access rights evaluation

The model of access rights contains time schedules and a table of holidays. A block diagram for access right evaluation can be seen in *Pic. 6*.



*Pic. 6: Simplified access rights evaluation*

## 8 Useful links

- Wiring diagrams: <http://techfass.cz/diagrams-aps-mini-plus-en.html>
- Program equipment: <http://techfass.cz/software-and-documentation-en.html>